

A Meteor Propagation Model Based on Fitting the Differential Equations of Meteor Motion



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Goal and Existing Models

Fully-Coupled Multi-Camera Trajectory Estimation
Requires a Propagation Model*

Single k^{th} Camera Motion Model:

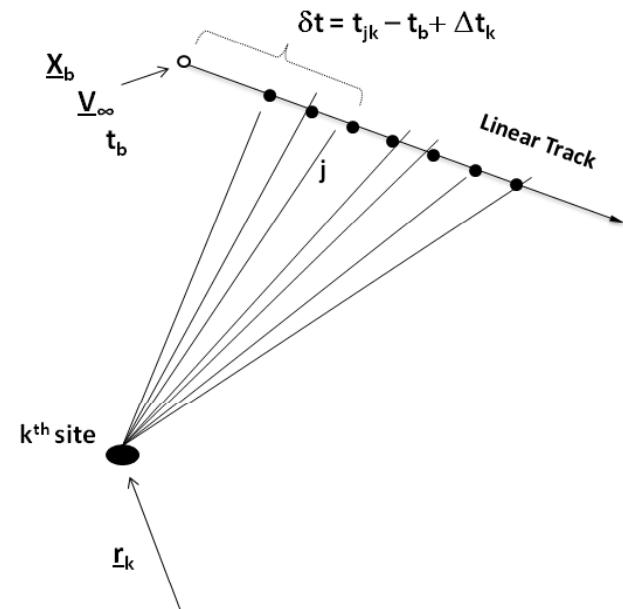
$$\underline{x}_k(t=j\delta_s) = \underline{x}_b + \underline{V}_{\infty} * [t + \Delta t_k - t_b] + a(t + \Delta t_k - t_b)$$

Published Propagation Models

$$x(t) = x_0 + V_e t$$

$$x(t) = x_0 + V_e t + a t^2$$

$$x(t) = x_0 + V_e t + C e^{kt}$$



Whipple F. L., and Jacchia L. G. (1957) "Reduction methods for photographic meteor trails." Smithsonian Contributions to Astrophysics 1, pp. 183-206

Does not fit a deeply penetrating fireball over the ENTIRE trajectory at once

* Gural, P (2012) "A new method of meteor trajectory determination applied to multiple unsynchronized video cameras" Meteoritics & Planetary Science ??? pp. 1-14. Also see IMC 2011 PPT presentation.

Dynamical Equations of Meteor Motion

Drag:

$$M \frac{dV}{dt} = -\frac{1}{2} c_d \rho_a V^2 S,$$

Straight Line Propagation:

$$\frac{dh}{dt} = -V \sin \gamma,$$

Mass Loss:

$$H * \frac{dM}{dt} = -\frac{1}{2} c_h \rho_a V^3 S$$

Assumptions

Isothermal Atmosphere: $\rho = \exp(-y)$

Mass – Shape Power Law: $\frac{S}{S_e} = \left(\frac{M}{M_e}\right)^{\mu}$

Dimensionless Parameters

Ballistic Coefficient: $a = \frac{1}{2} c_d \frac{\rho_0 h_0 S_e}{M_e \sin \gamma},$

Mass Loss Parameter: $\beta = (1 - \mu) \frac{c_h V_e^2}{2 c_d H^*}$

Power Law (rotation?): $\mu = \log_m s$

Solutions and Equation for dV / dt

Mass as a function of Velocity:

$$m(v) = \exp\left(-\beta \frac{1-v^2}{1-\mu}\right)$$

*Normalized
Variables*

Height as a function of Velocity:

$$y(v) = \ln 2\alpha + \beta - \ln(\bar{E}i(\beta) - \bar{E}i(\beta v^2))$$

Exponential Integral:

$$\bar{E}i(x) = \int_{-\infty}^x \frac{e^z dz}{z}$$

Acceleration

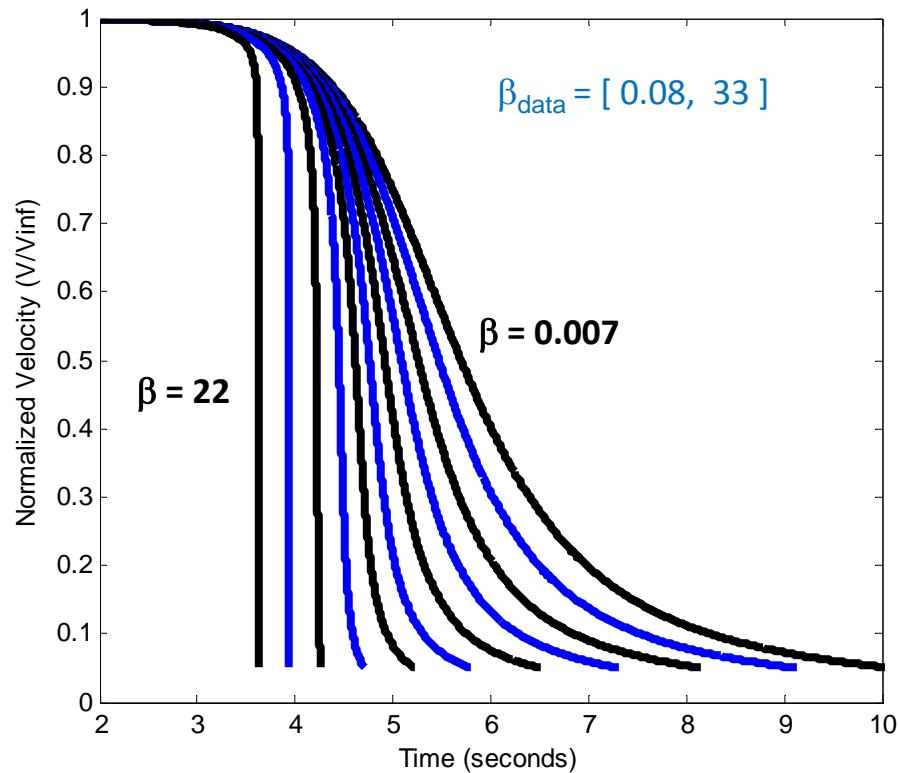
$$dv / dt = (-V_e \sin\gamma / 2 h_o) v^2 \exp(-\beta v^2) [\bar{E}i(\beta) - \bar{E}i(\beta v^2)]$$

Function ONLY of a scale factor and β ! → How to obtain $x(t, \beta)$?

Velocity and Position Profiles

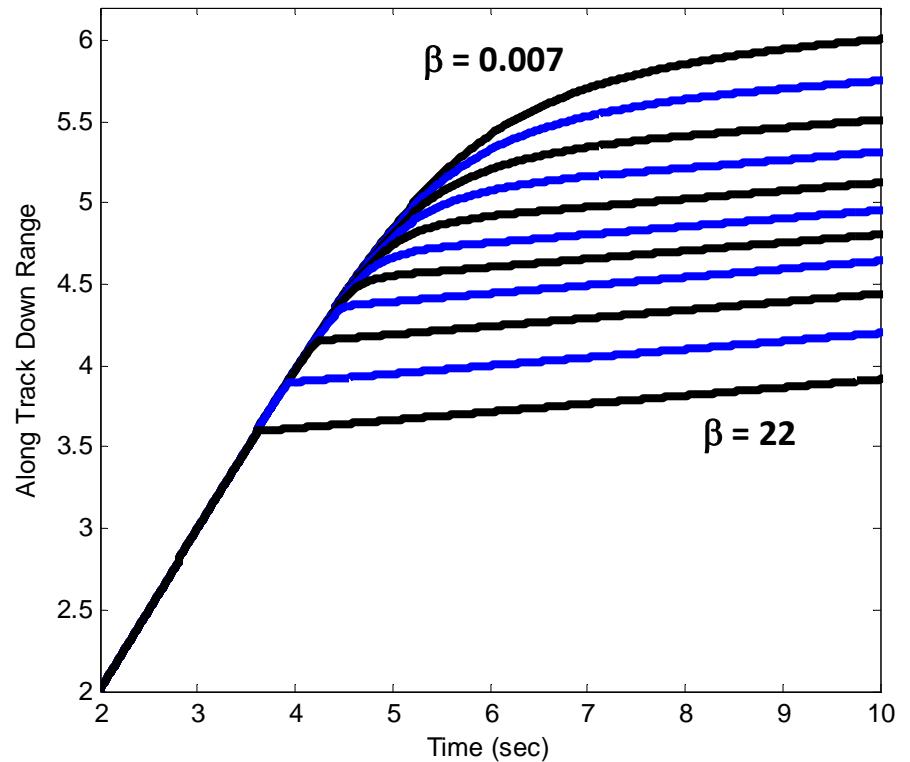
$$t = \left(-2 h_o / v_e \sin\gamma \right) \int_1^v dv \, v^{-2} \exp(\beta v^2) / [\bar{Ei}(\beta) - \bar{Ei}(\beta v^2)]$$

Velocity $v(t, \beta)$



$\int dt \rightarrow$

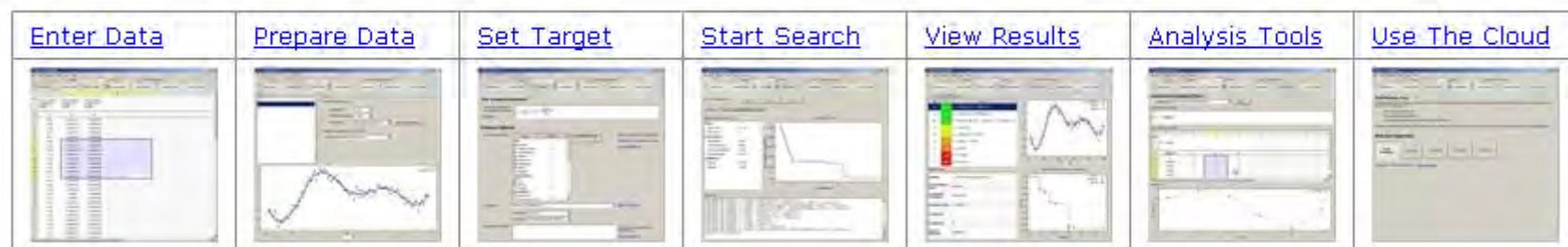
Position $x(t, \beta)$



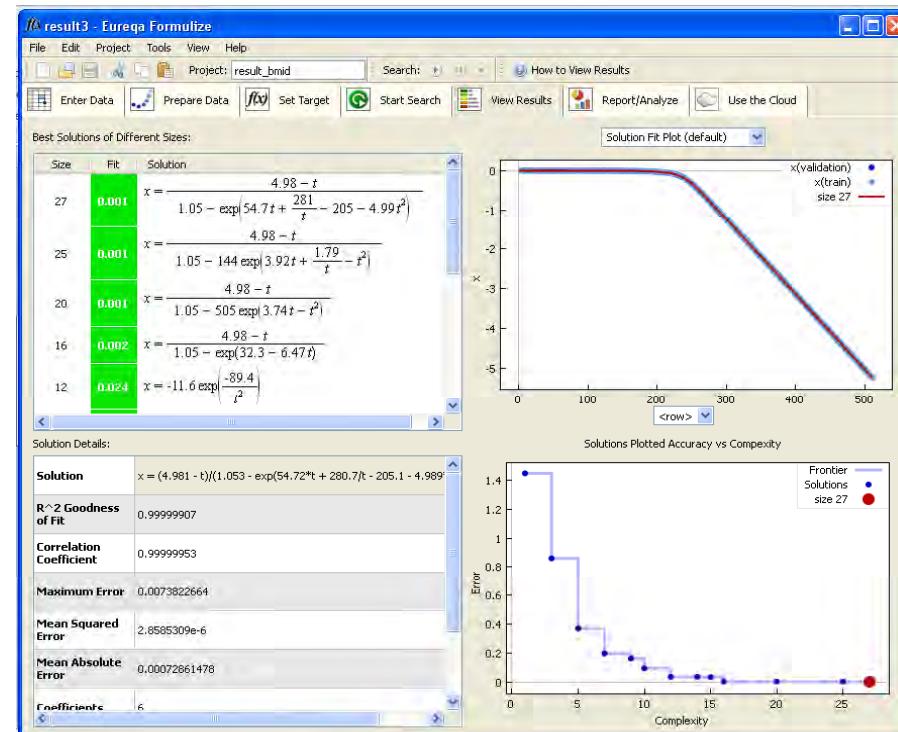
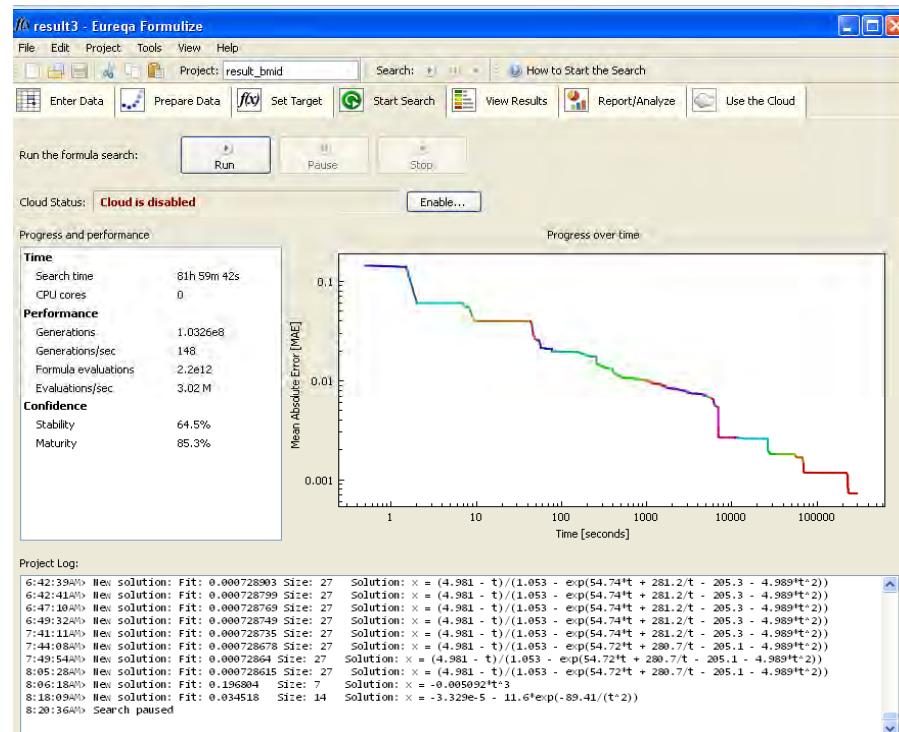
$\beta = 22.003 \quad 12.603 \quad 8.132 \quad 5.896 \quad 4.669 \quad 3.797 \quad 2.989 \quad 2.222 \quad 1.519 \quad 0.755 \quad 0.007$

Eureqa Formulize

“A software tool for detecting equations and hidden mathematical relationships in your data”



$$f(x) = + - \times \div \sin x \cos^{-1}x \tanh x e^x \log x ! y^x \sqrt{\dots}$$



“Best” Model Found – Thus Far

$$x(t) = t + (c_1 + c_2 t) / \{ c_3 + c_4 \exp[(c_5 + c_6 t) / (c_7 + \exp(t)) + c_8 t] \}$$

$$c_1 = +0.34087 + 2.6517 \beta$$

$$c_2 = -0.50104 - 2.6621 \beta + 0.89817 \beta^2 - 0.097926 \beta^3$$

$$c_3 = +0.81913 + 4.2046 \beta - 1.5428 \beta^2 + 0.16662 \beta^3$$

$$c_4 = +19.548 + 109.15 \beta - 41.522 \beta^2 + 4.0013 \beta^3$$

$$\beta < 3$$

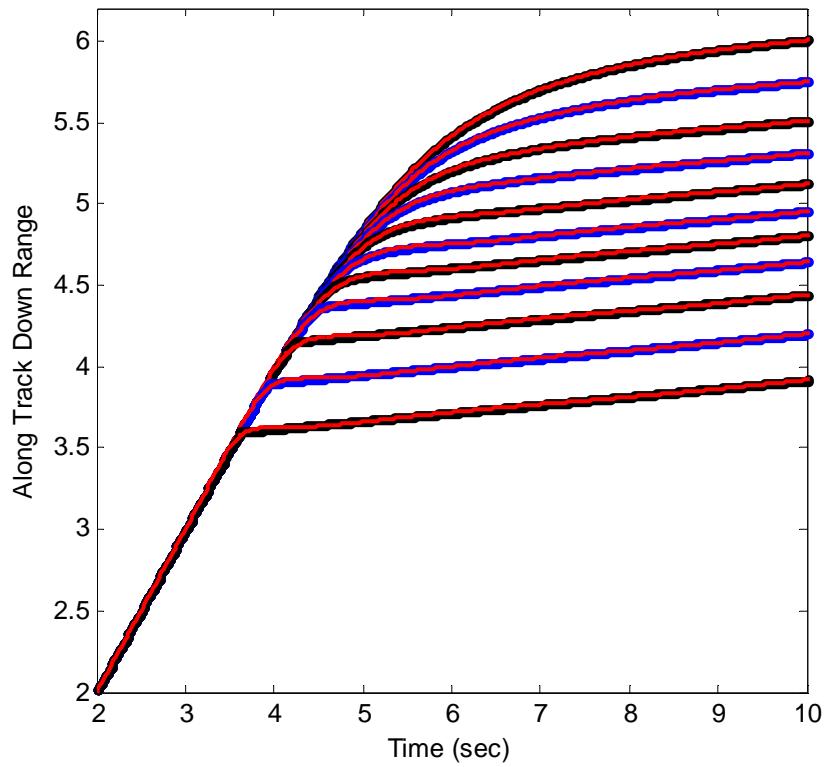
$$c_5 = +179.04 + 425.61 \beta - 65.534 \beta^2$$

$$c_6 = +28.46 - 77.083 \beta + 9.1122 \beta^2$$

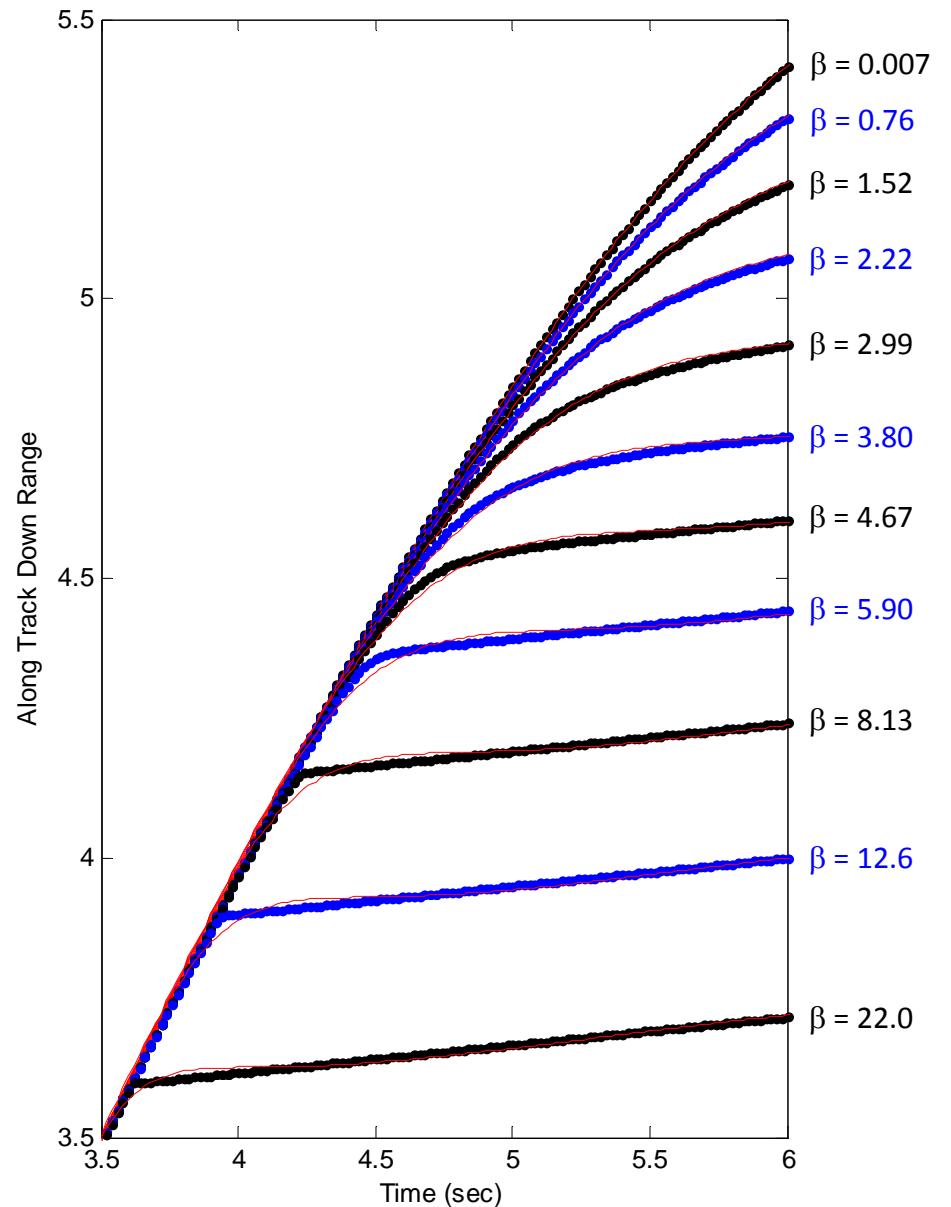
$$c_7 = +45.027 + 129.66 \beta - 228.04 \beta^2 + 223.16 \beta^3 - 124.53 \beta^4 \\ + 39.119 \beta^5 - 6.4418 \beta^6 + 0.42978 \beta^7$$

$$c_8 = +0.40731 + 0.033279 \beta$$

Performance Fit Results



80% of Fireballs had $\beta < 3$



Next Steps

- **Find a model valid for high mass loss coef $\beta > 3$**
 - *Continue with Eureqa Formulize, use other functions*
 - *Remove the terminal velocity (dark flight) portion of data → Eureqa*
 - *Possibly merge two models*
- **Test on actual fireball tracks**
- **Incorporate into the multi-parameter fit trajectory code**
 - *Add new propagation model(s)*
 - *Errors per measurement & associated cost function*
 - *Switch from simplex to simulated-annealing minimization*

Assuming I am not too distracted by Spectral-CAMS !